

**AP Physics B**  
**Chapters 1-2**  
**1 dimensional kinematics**

# Chapter 1

## Introduction, Measurement, Estimating



# Unit conversions

- Unit cancellation method
- Example – convert 100 miles/hour into feet/sec

# Chapter 2

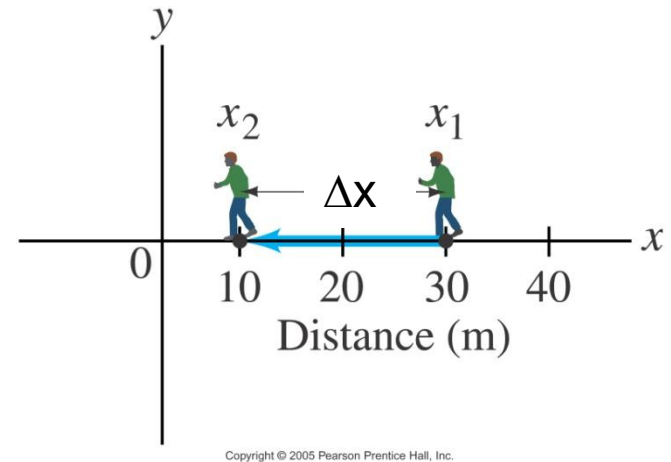
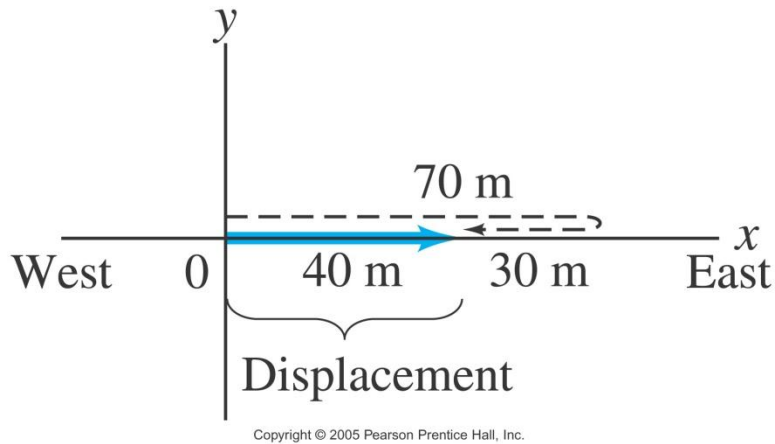
## Describing Motion: Kinematics in One Dimension



# Kinematic Vectors and Scalars

- 2 scalar quantities (magnitude only)
  - distance
  - speed
- 3 vector quantities (magnitude and direction)
  - displacement
  - velocity
    - average
    - instantaneous
  - acceleration

# Distance and Displacement



- distance walked = 100 m, 20 m
- displacement = + 40 m, - 20 m
  - $\Delta$  means “change in”
  - always calculated as (final – initial)
  - $\Delta x = 40 - 0$       or  $\Delta x = 10 - 30$

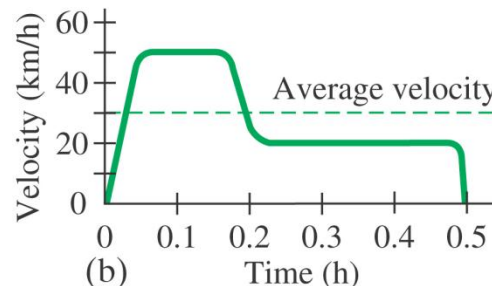
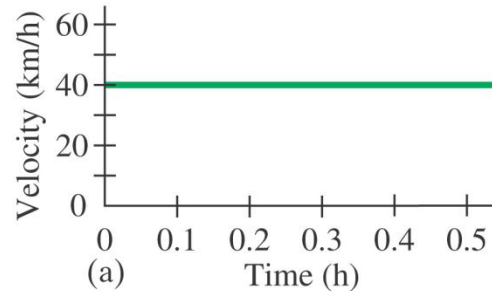
# Speed and Velocity

- average speed = distance/time

- average velocity 
$$\bar{v} = \frac{\text{displacement}}{\text{time}} = \frac{\Delta x}{t} = \frac{x_f - x_0}{t}$$

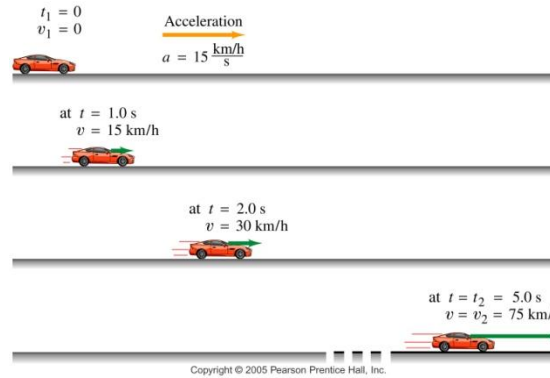
– negative velocity means motion in negative direction

- instantaneous velocity – at an instant in time

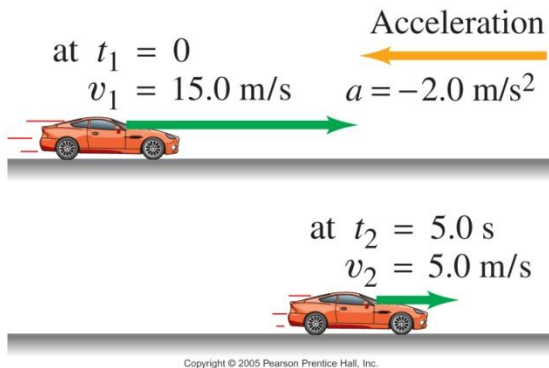


# Acceleration

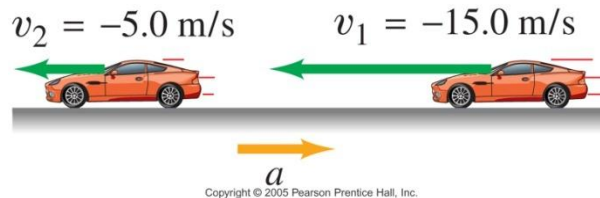
$$\bar{a} = \frac{\Delta v}{t} = \frac{v - v_0}{t}$$



1) + acceleration  
increasing speed in + direction



2) - acceleration  
decreasing speed in + direction



3) + acceleration  
decreasing speed in - direction

4) - acceleration  
increasing speed in - direction



## Kinematic equations – constant acceleration only

$$1) v_f = v_0 + at$$

$$2) \Delta x = \bar{v} \cdot t = \left( \frac{v_f + v_0}{2} \right) t$$

$$3) \Delta x = v_0 t + \frac{1}{2} at^2$$

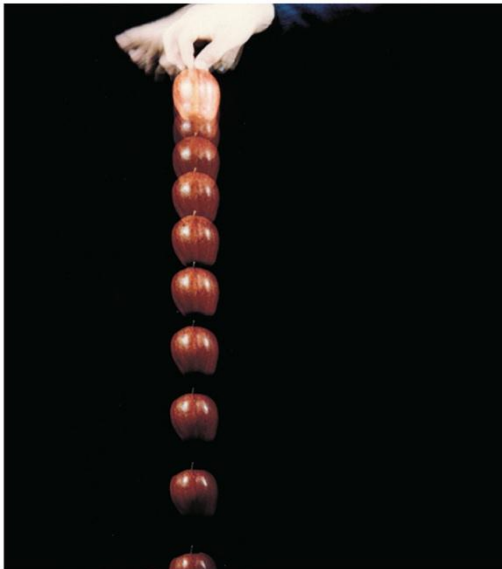
$$4) v_f^2 = v_0^2 + 2a(x_f - x_0)$$

- 5 kinematic variables
  - one variable missing from first 3 equations
- key to solving kinematic problems is identifying givens and choosing correct equation to solve for desired quantity

must be able to solve problems for algebraic solutions

# Free Fall

- demo
- all objects accelerate at same rate if air resistance is neglected  $g = 9.8 \text{ m/s}^2$
- replace  $a = -g$  in kinematic equations



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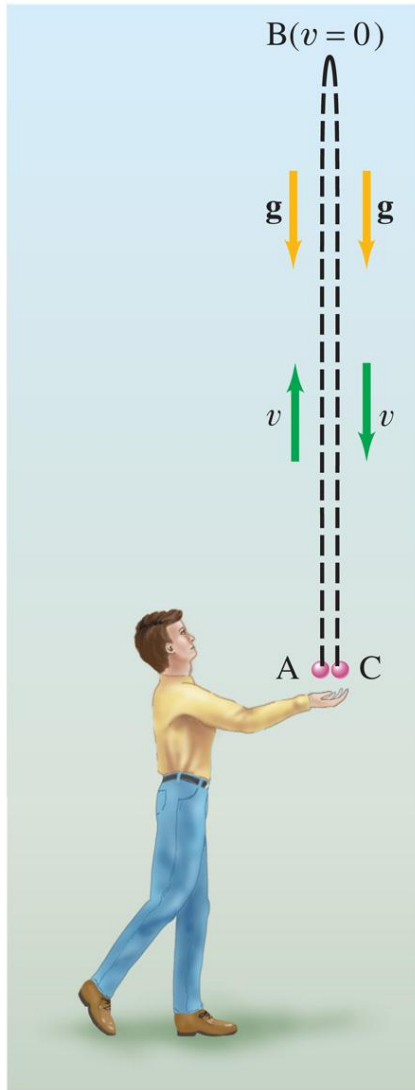


(a)



(b)

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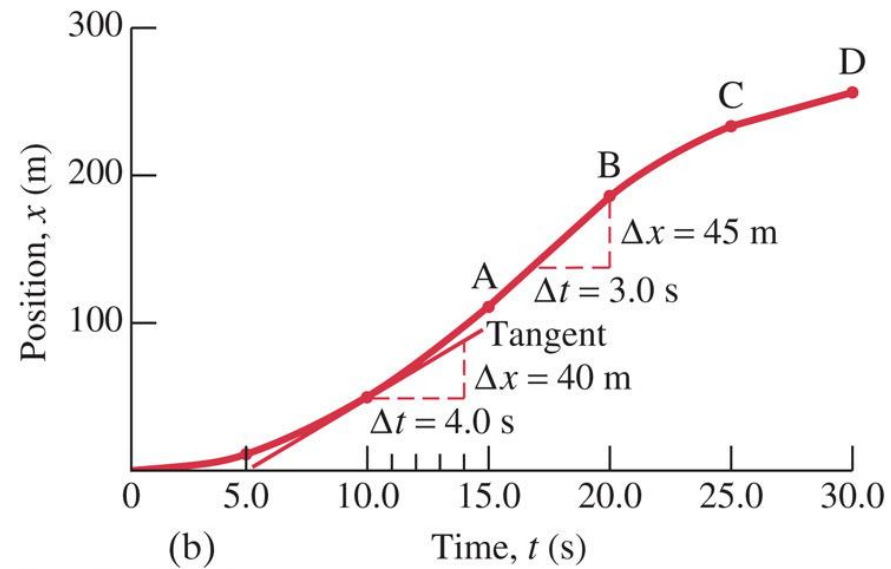
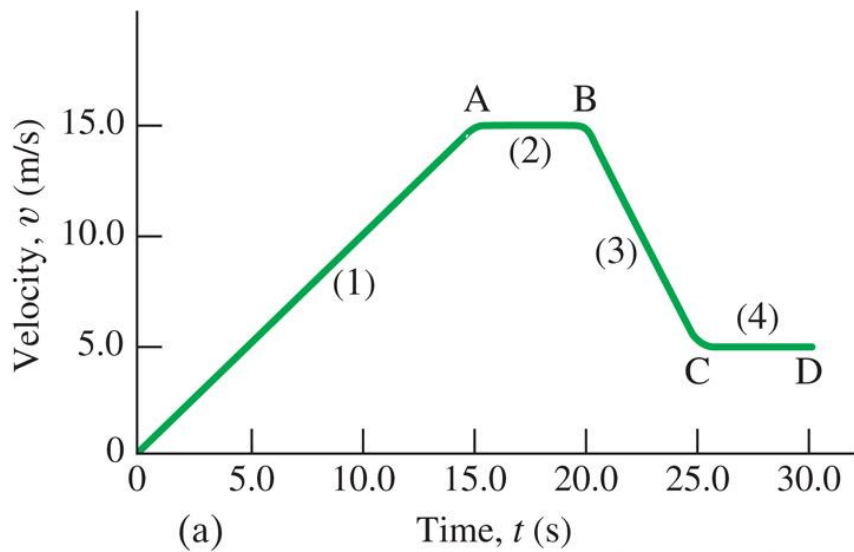


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- vectors pointing up are +
- vectors pointing down are –
- motion is symmetrical
  - paths up and down are identical and opposite
- object stops at maximum height for an instant
- **acceleration vector is always negative – always pointing down – no matter what direction object is moving**

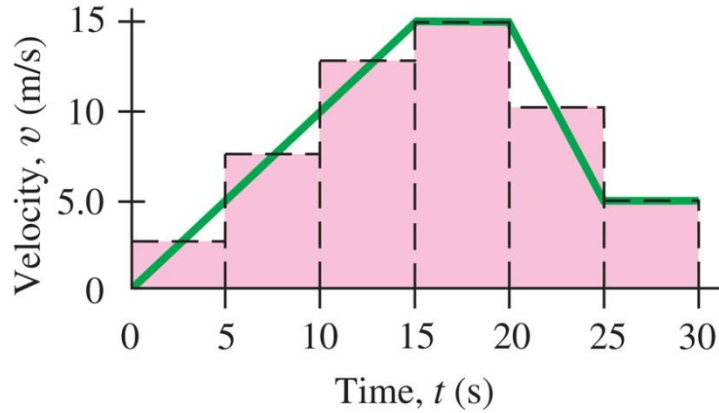
# 2-8 Graphical Analysis of Linear Motion

- slope of position – time graph = average velocity
- slope of velocity – time graph = average acceleration

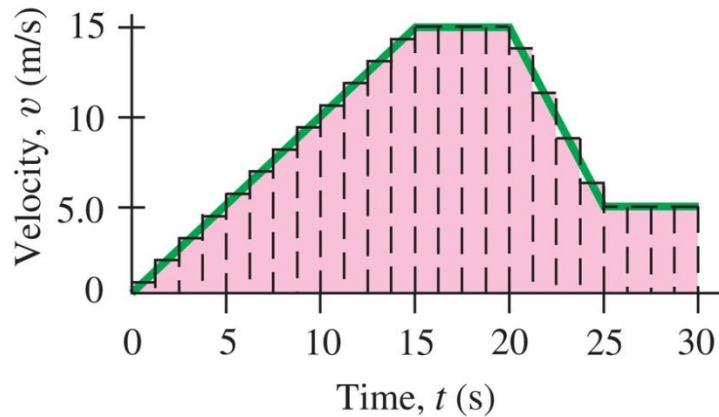


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- area under velocity – time graph = displacement

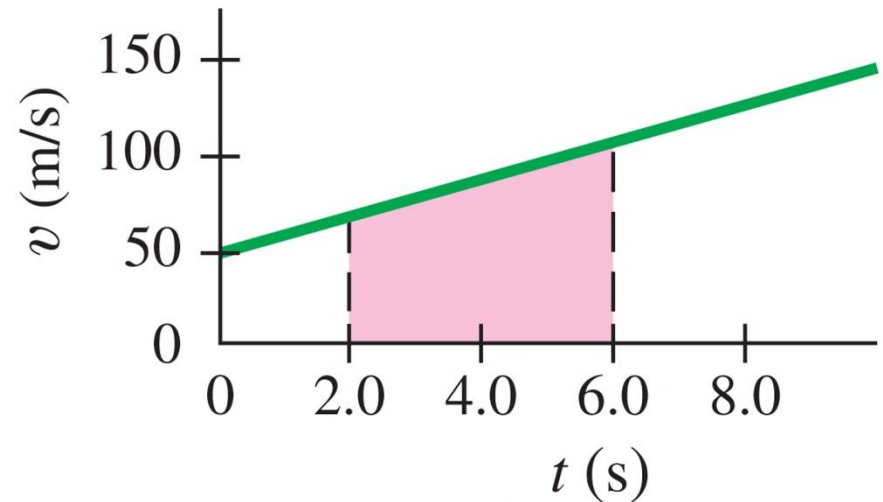


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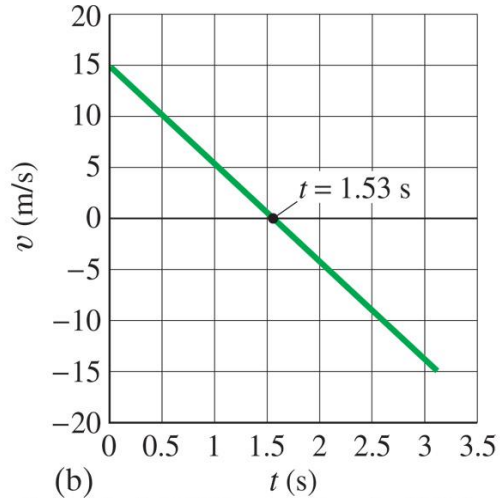
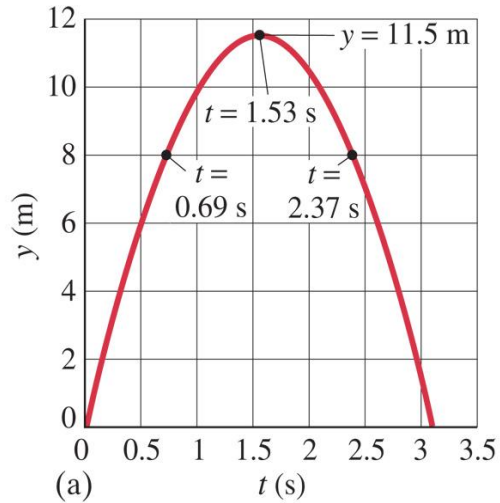
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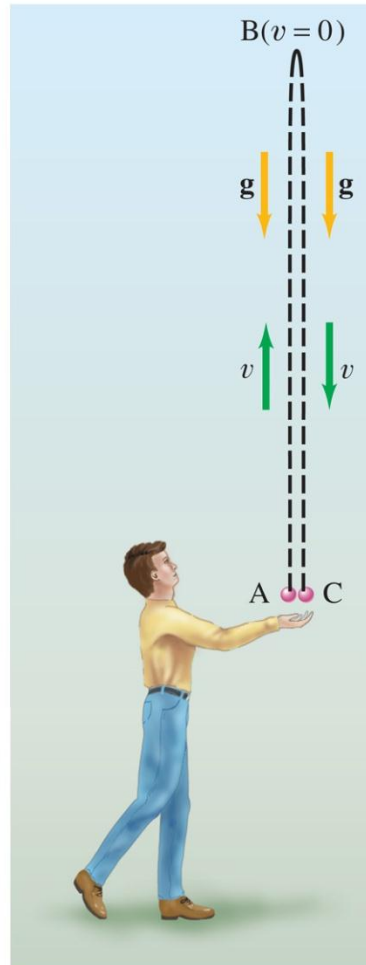


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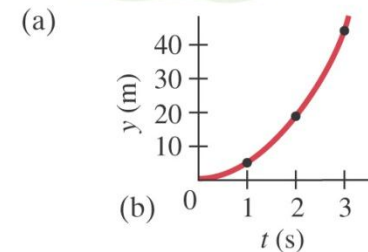
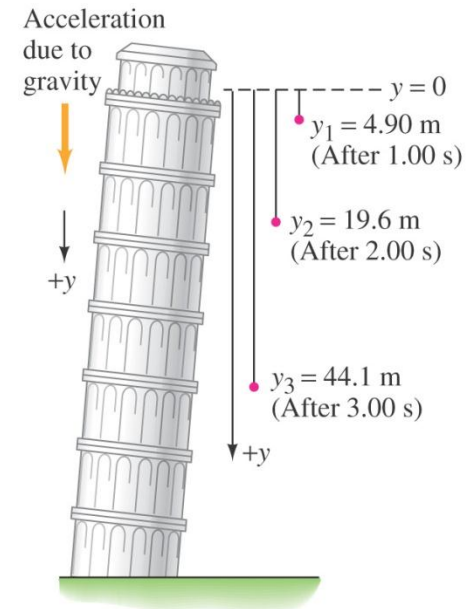
# Shapes of kinematic graphs



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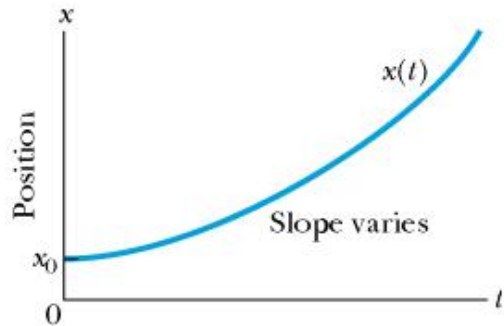


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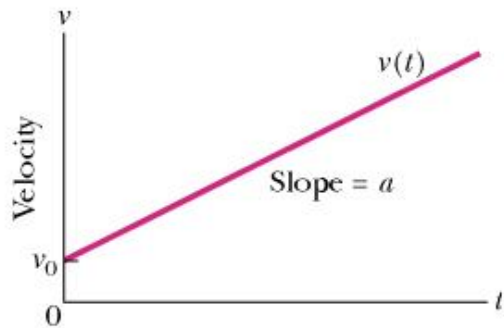


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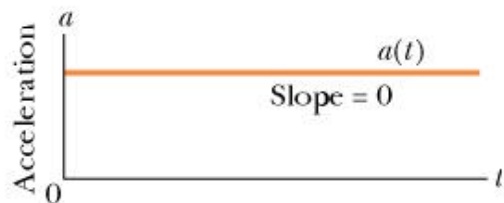
# Kinematic graphs for constant acceleration



(a)

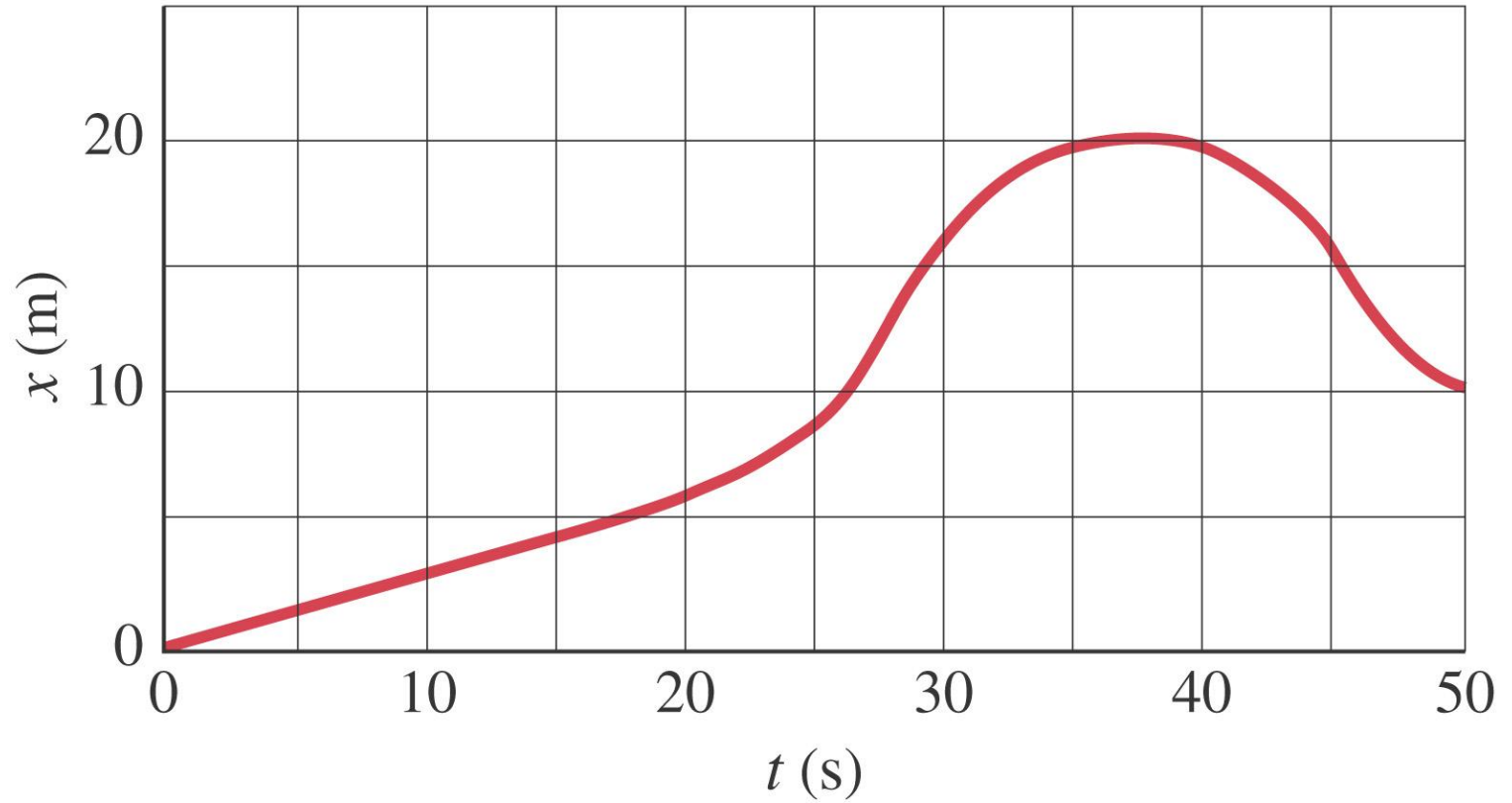


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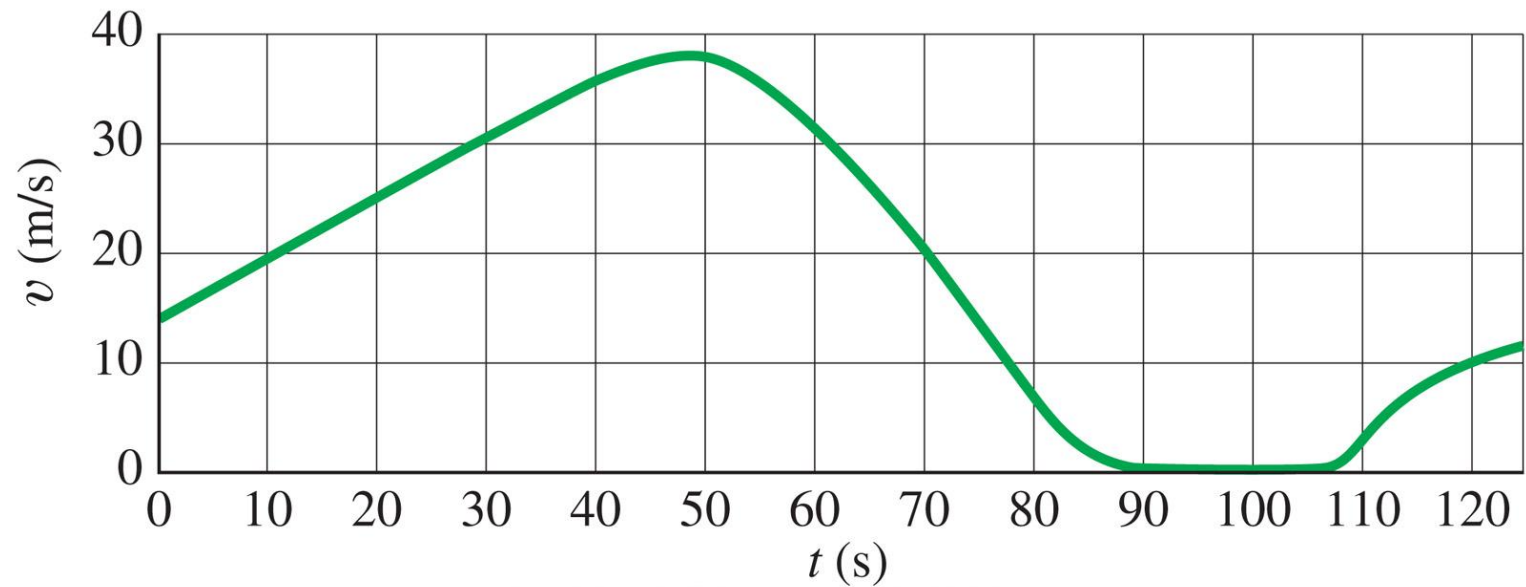
(c)

- position – time graph is parabolic
- velocity – time graph is linear
- acceleration – time graph is constant



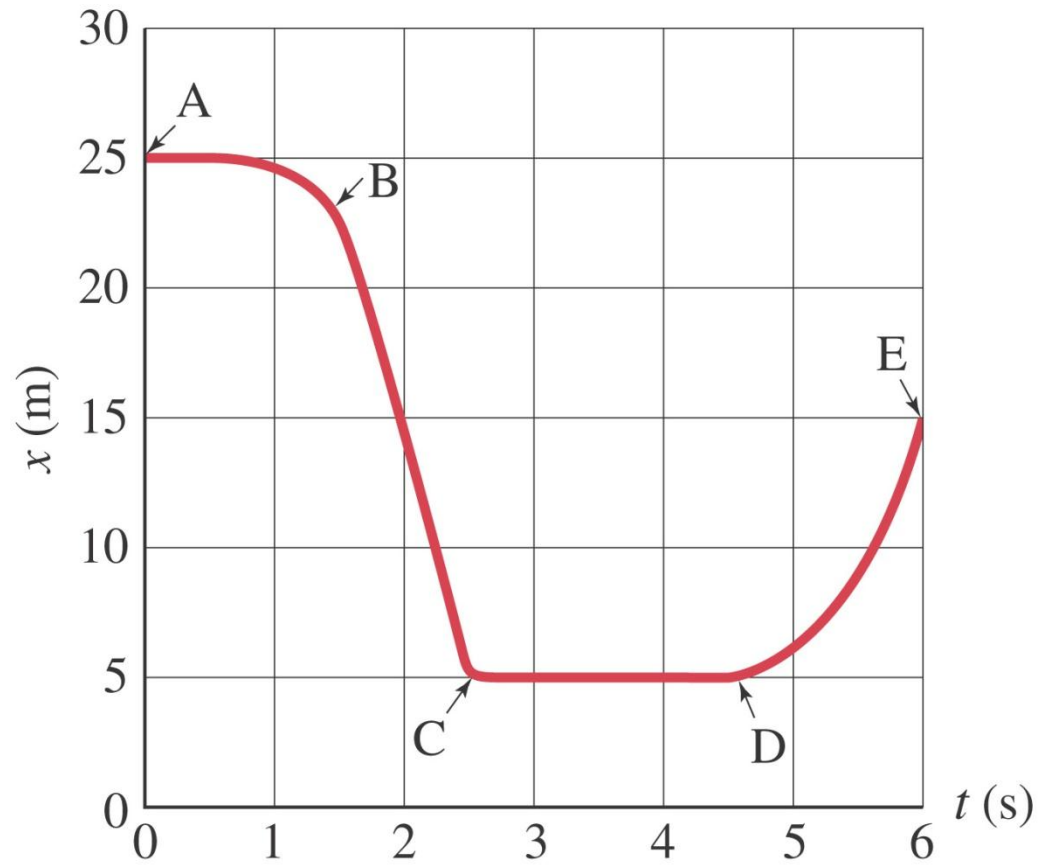
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# Problem 2 – 56



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